Training to use EUS-FNA: It is time to give up the human hands-on approach?

In this issue, Hoshi K et al evaluate their endoscopic ultrasound fine-needle aspiration (EUS-FNA) training model [1]. This model involves use of an isolated porcine stomach and is believed to be realistic, simple, and inexpensive. Training in EUS, and mainly in EUS-FNA, is really challenging because use of the procedure is growing and it is key to medical management, particularly in oncology. EUS-FNA requires expertise and practitioners need to be trained to perform the procedure. More than 10 years ago, the American Society for Gastrointestinal Endoscopy determined that achieving competency in EUS procedures required a minimum of 150 supervised cases, at least 50 of which were EUS-FNA [2]. Other recent recommendations have stated a threshold of 75 EUS-FNA cases [2]. Results of a follow-up study have shown that a special training program could significantly reduce the median number of passes after 100 EUS procedures and the morbidity after 200 procedures [3]. Few training centers offer minimal training during a 1-year curriculum. Over the past 10 years, our team has developed a special nationwide learning and training program for EUS and EUS-FNA that includes 2 weeks of theoretical courses involving video libraries, a computer-based virtual model, tabletop phantom models, ex vivo models with video libraries, a computer-based virtual model, tabletop phantom models, ex vivo models that use isolated organs from animals, and finally live pigs. From an anatomical perspective, in comparison with human beings, training to perform US on live pigs is the most exciting and realistic way to learn. However, it is also the most expensive and the model to which the skills are gained. A training model for EUS-FNA should be realistic, that is, the image and scope positioning should be consistent. The model should also be easy to reproduce and the training widely available and inexpensive so that expertise can be diffused. Durability, too, is important, meaning that the model holds up through many procedures done by inexperienced hands in a training session of at least a half day.

Many forms of training in EUS-FNA have been proposed for young practitioners, including didactic materials with video libraries, a computer-based virtual model, tabletop phantom models, ex vivo models that use isolated organs from animals, and finally live pigs. From an anatomical perspective in comparison with human beings, training to perform US on live pigs is the most exciting and realistic way to learn. However, it is also the most expensive and the model to which it is the most difficult to gain access because of restrictive laws and the costs involved (the price of the animal, the veterinarian, the animal laboratory, etc.) [2,4]. Fritscher-Ravens et al recently demonstrated that porcine lymph nodes in live pigs are a good model for acquiring EUS-FNA competence [5]. Models with isolated animal organs may be the best compromise in terms of realism, cost, and availability. The organs most often used are pig stomach to simulate false submucosal tumors, such as in the paper by Hoshi et al. that appears in this issue (chicken tenderloins), sutured colon segments filled with various fluid contents to simulate pseudocystic lesions, or grapes to mimic lymph

When to do EUS-training is another question. Training in EUS-FNA typically is reserved for physicians who have completed residency or are seeking postgraduate credentials because it requires both cognitive and technical competencies and because EUS scopes are not available in all endoscopy units. Finally, the cornerstone for EUS and EUS-FNA training is the method by which the skills are gained. A training model for EUS-FNA should be realistic, that is, the image and scope positioning should be consistent. The model should also be easy to reproduce and the training widely available and inexpensive so that expertise can be diffused. Durability, too, is important, meaning that the model holds up through many procedures done by inexperienced hands in a training session of at least a half day.

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nodes [6]. Isolated organs can be surrounded with water, tapioca, agar gel or gelatin to enhance the accuracy of US. Based on current practice with US and during repeated procedures by inexperienced hands, however, these models could be more or less rapidly damaged or destroyed. Therefore, achieving realistic properties for and durability of models for EUS-FNA training remains challenging. Many teams are working to develop a realistic, efficient, durable, and cheap model for teaching EUS-FNA. Guidelines from the European Society of Gastrointestinal Endoscopy recommend a combination of different simulators and, if possible, a live swine model to achieve competency in performing EUS-FNA [7].

The model developed by Hoshi’s team is a new contribution for improving training in EUS-FNA [1]. In order for skills in EUS-FNA to be diffused, training models that are cheap, realistic, and efficient are required because achieving proficiency with the procedure requires skills and a long learning curve with a minimum threshold, which is difficult to attain and to validate [8]. But the availability of that kind of model needs to be increased and it should be validated in comparative studies and its real impact on the quality of EUS-FNA assessed. Therefore, it is definitely time to give up human hands-on training in EUS-FNA.

Competing interests: None

References
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