Innovative Solution for Grasping Forceps Support Suction to Facilitate Uniportal Video-Assisted Thoracoscopic Surgery

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Abstract

Uniportal video-assisted thoracoscopic surgery has been limited to the use of very few instruments, which but at least include energy device, grasping forceps, and suction. The last two instruments must be temporarily replaced by each other in response to situation. This step prolongs operative duration and potentially impairs the surgical efficiency. We describe a novel instrument design of grasping forceps support suction. Its continuous suction can clear the smoke and blood simultaneously to keep the operative field dry and clean, minimize the requirement to exchange surgical devices, and allow for optimized surgical workflow.

Keywords

► VATS
► instrument
► surgical technique

Introduction

Surgeons apply grasping forceps and suction in minimally invasive surgical environments to cooperate with the energy device that handled in right hand.1 However, unlike in mini-thoracotomy or even multiport video-assisted thoracoscopic surgery (VATS), where access is readily available or instrument motion is relatively unrestricted, the use of these instruments in uniport VATS has been limited by the single surgical corridors. The two devices possibly interact with each other when they are maneuvered, and must be temporarily removed and replaced during surgery (►Fig. 1).

Such frequent instrument exchange during endoscopic surgery has several shortcomings: (1) it is time-consuming; (2) it disrupts the flow of the procedure, and can break the concentration of the surgeon; (3) it poses a safety risk to the patient. Due to the limited view obtained with most endoscopes, there may be instances during an insertion or removal when the instrument cannot be seen while it is still inside the patient. These “blind” episodes are potential causes of trauma that can be minimized by reducing the frequency of instrument exchanges.2,3

With the aim of solving this problem, we developed a novel instrument of grasping forceps support suction. It minimized the requirement to exchange surgical devices when performing uniportal VATS, and allowed for new maneuvers that optimized surgical workflow, such as the ability to ensure continuous suction during surgery, maintaining a dry surgical field and an improved endoscopic visibility.

Structure of the Grasping Forceps Support Suction

Our device (►Fig. 2) was adapted from standard grasping forceps originally developed for target tissue holding that were augmented to co-function as lymph node grippers. The suction tube, which is taken from a disposal vein infusion set, accompanied the shaft of the instrument, and then the aspiration system is connected to the handle. As such the
instrument tip does additionally function as an aspirator while it still serves its original function as gripper.

This device works identically to both a standard clamp forceps and a dedicated suction. When the clamp grasps or handles the target tissue, the continuous suction permits an improved endoscopic visualization via blood, smoke, and other cautery by-products synchronized cleaning.

Clinical Experience

After its 6 months clinical application, our experience demonstrated that the combinations of two instruments provided maximal efficiency in workflow and reduced the requirements to remove and reinsert surgical devices when suction was intermittently needed.

Discussion

Improved efficiency in the performance of a procedure is one of the primary goals of instrument design. Multifunctionality clearly plays a role in making an instrument more effective and hence more popular among surgeons. Solely improving the primary function of an instrument at the detriment of secondary and tertiary uses decreases its flexibility and could therefore limit its clinical popularizing. By somehow combining the function of two of the main devices, the number of device changes necessary to complete the procedure could be reduced. This would potentially heighten the surgical effectiveness, shorten the operative duration, and lessen the underlying trauma to the patient during an instrument exchange. This is more important in uniportal VATS due to its very limited access.

Attending to the combination of a grasping forceps and a suction device, our newly developed instrument works as dual-function, it offers several advantages compared with what they currently are. Namely, it potentially increases surgical efficiency and enhances workflow by expanding the functions of standard clamping forceps to dually serve as suction apparatus. It allows a simultaneous clearing of smoke and blood resulting from electrosurgery during surgery. Meanwhile, it also allows an increased surgical efficiency by minimizing the repetitive removal/insertion of instruments, thereby reducing the risk of interfering with each other, and potentially reducing operative duration. Finally, it reduces the reliance on assistant(s) and increases
surgical proficiency. These advantages render this novel, dual-functional, minimal-access device has the potential to make a substantial contribution to uniportal VATS, minimally invasive or traditional open surgery.

Disclaimer
The German Society for Thoracic and Cardiovascular Surgery (DGTHG) and The Thoracic and Cardiovascular Surgeon neither endorse nor discourage the use of the new technology described in this publication.

Conflict of Interest
The patent of this instrument is waived to facilitate its clinical distribution.

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Xugang Zhang MD, PhD and Lei Yang MD have made a great deal of contribution to instrument design, testing, and usage.

References