Miniature-probe endoscopic ultrasonography using a rubber balloon to evaluate gastrointestinal carcinomas in poor underwater conditions

Miniature-probe endoscopic ultrasonography (m-EUS) is routinely used to diagnose the invasion depth of gastrointestinal carcinomas [1, 2]. However, the efficacy of EUS is sometimes limited in locations such as the esophagus and esophagogastric junction, where water does not accumulate sustainably [3, 4]. A rubber balloon (MAJ-213; Olympus, Tokyo, Japan) is clinically available for attaching to a convex-type EUS probe [5]. We describe a novel m-EUS method using this rubber balloon without the need for intraluminal underwater conditions (▶ Fig. 1; ▶ Video 1).

A 74-year-old man presented with a 25-mm protruding carcinoma located at the esophagogastric junction (▶ Fig. 2). EUS with a high-frequency 20-MHz miniature probe (UM-3R; Olympus) was performed to diagnose the tumor invasion depth. However, conventional m-EUS could not capture an underwater image because the water passed easily into the stomach. It was for this reason that we developed and used our m-EUS system, as follows. First, the rubber balloon was attached to a conventional endoscope (GIF-H260Z; Olympus) and fixed with tape. The endoscope reached the target lesion and provided an acceptable endoscopic view (▶ Fig. 3). Now the balloon was filled with water using the water jet function and the miniature probe inserted within the water-filled balloon. m-EUS revealed a well-demarcated hypoechoic mass within the second layer and an intact submucosal layer (▶ Fig. 4), and diagnosed the tumor depth as within the mucosa. In accordance with the EUS diagnosis, endoscopic submucosal dissection was completed. Histological examination confirmed curative resection of adenocarcinoma with mucosal invasion. This method was also useful in another patient for diagnosing the invasion depth of a signet ring cell carcinoma located in the antrum of the remnant stomach where there was poor water pooling (▶ Fig. 5).

m-EUS using a rubber balloon is simple and effective for resolving poor underwater visual conditions.

Competing interests

The authors declare that they have no conflict of interest.
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